

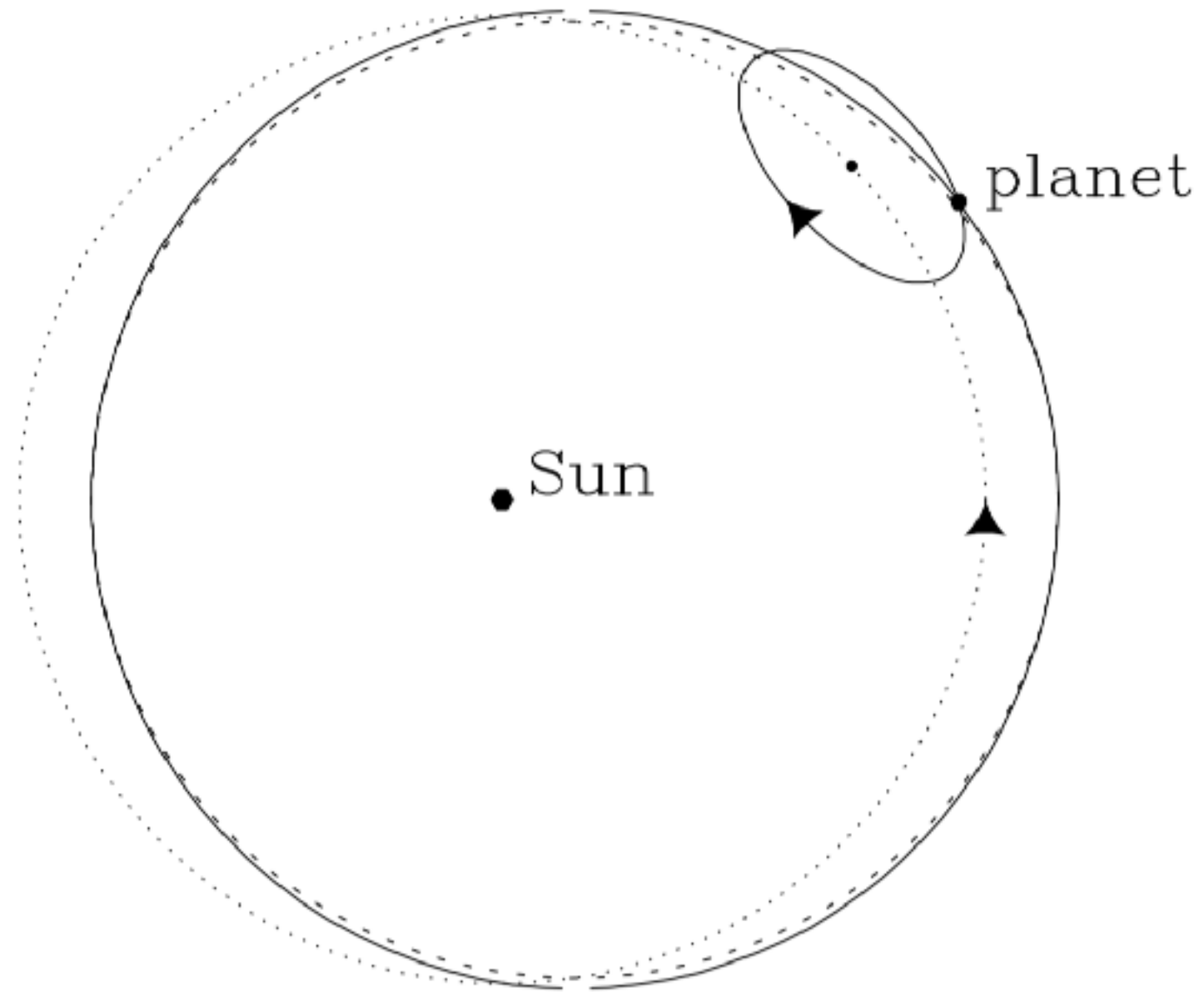
The epicyclic approximation for
orbits in axisymmetric potentials

BT2, §3.2.3

Overview

In axisymmetric potentials, nearly circular orbits can be approximated as **retrograde elliptical motion** with **epicyclic frequency κ** on top of circular motion of a **guiding center** with **angular frequency Ω** and same L_z

$$\kappa = \sqrt{d\Omega^2 / d \ln R + 4\Omega^2}$$



Main steps of the epicyclic approximation derivation

- ▶ Write general EOMs in cylindrical coordinates
- ▶ Specialize to axisymmetric case and define effective potential Φ_{eff} , such that R, z EOMs look like Cartesian EOMs in Φ_{eff}
- ▶ Show that Φ_{eff} minimum (guiding center) follows a circular orbit around the center of the system
- ▶ Taylor expand Φ_{eff} around its minimum and show that motion in (x, y, z) coordinates in the frame of the guiding center can be approximated as simple harmonic oscillations with frequencies κ (in x, y) and ν (in z)
- ▶ Derive expression for κ in terms of the Ω profile of the system
- ▶ Obtain explicit solutions for $(x(t), y(t), z(t))$ elliptic motion

Gravitational dynamics in cylindrical coordinates

$$\mathbf{r} = R\hat{\mathbf{e}}_R + z\hat{\mathbf{e}}_z$$

$$\mathbf{v} = \dot{R}\hat{\mathbf{e}}_R + R\dot{\phi}\hat{\mathbf{e}}_\phi + \dot{z}\hat{\mathbf{e}}_z$$

$$\mathbf{a} = (\ddot{R} - R\dot{\phi}^2)\hat{\mathbf{e}}_R + (2\dot{R}\dot{\phi} + R\ddot{\phi})\hat{\mathbf{e}}_\phi + \ddot{z}\hat{\mathbf{e}}_z$$

$$\nabla\Phi = \frac{\partial\Phi}{\partial R}\hat{\mathbf{e}}_R + \frac{1}{R}\frac{\partial\Phi}{\partial\phi}\hat{\mathbf{e}}_\phi + \frac{\partial\Phi}{\partial z}\hat{\mathbf{e}}_z$$

Equations of motion:

$$\mathbf{a} = -\nabla\Phi \quad \Rightarrow \quad \left\{ \begin{array}{l} \ddot{R} - R\dot{\phi}^2 = -\frac{\partial\Phi}{\partial R} \\ 2\dot{R}\dot{\phi} + R\ddot{\phi} = \frac{1}{R} \frac{d(R^2\dot{\phi})}{dt} = -\frac{1}{R} \frac{\partial\Phi}{\partial\phi} \\ \ddot{z} = -\frac{\partial\Phi}{\partial z} \end{array} \right.$$

Axisymmetric case

$$\Phi = \Phi(R, z) \Rightarrow \frac{\partial \Phi}{\partial \phi} = 0 \quad \Rightarrow \quad \frac{d(R^2 \dot{\phi})}{dt} = 0$$

$$\Rightarrow L_z = R^2 \dot{\phi} = \text{const.}$$

z component
of angular
momentum

$$\Rightarrow \dot{\phi} = \frac{L_z}{R^2}$$

Reformulate R, z EOMs
using this result:

$$\ddot{R} = -\frac{\partial \Phi}{\partial R} + \frac{L_z^2}{R^3} = -\frac{\partial \Phi_{\text{eff}}}{\partial R}$$

$$\ddot{z} = -\frac{\partial \Phi_{\text{eff}}}{\partial z}, \text{ where } \Phi_{\text{eff}} \equiv \Phi + \frac{L_z^2}{2R^2}$$

I.e., motion in R, z modeled as oscillations in effective potential Φ_{eff}

Coordinates of the guiding center = Φ_{eff} minimum

Coordinates (R_g, ϕ_g, z_g) of the Φ_{eff} minimum satisfy:

$$0 = \frac{\partial \Phi_{\text{eff}}}{\partial R} = \frac{\partial \Phi}{\partial R} - \frac{L_z^2}{R^3}$$

$$0 = \frac{\partial \Phi_{\text{eff}}}{\partial z}$$

Assume that Φ is symmetric about z . Then the last equation is true everywhere in $z=0$ plane and the first holds in that plane where

$$\left(\frac{\partial \Phi}{\partial R} \right)_{(R_g, 0)} = \frac{L_z^2}{R_g^3} = R_g \dot{\phi}_g^2 \quad \text{centripetal acceleration of circular orbit of radius } R_g$$

I.e., R, z oscillate about circular orbit of radius R_g and angular momentum L_z

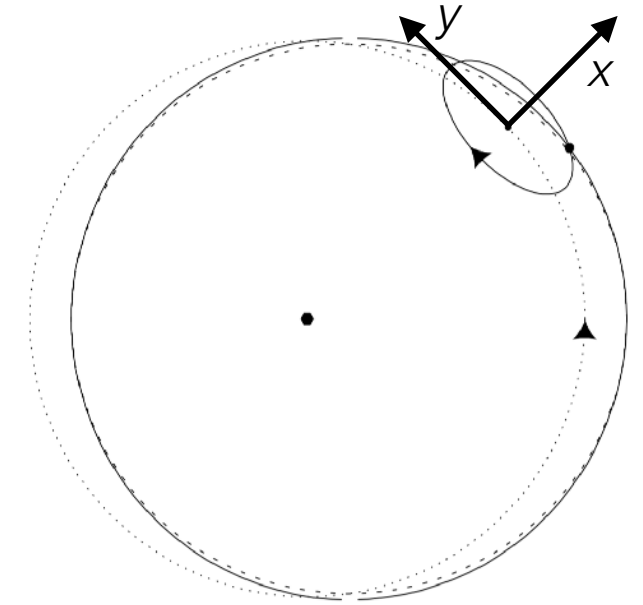
EOMs relative to guiding center

For small $x \equiv R - R_g$,

0 (can add arbitrary const.)

0 ($(R_g, 0)$ is Φ_{eff} minimum)

$$\Phi_{\text{eff}} = \Phi_{\text{eff}}(R_g, 0) + \frac{\partial \Phi_{\text{eff}}}{\partial R} \Big|_{(R_g, 0)} x + \frac{\partial \Phi_{\text{eff}}}{\partial z} \Big|_{(R_g, 0)} z + \frac{1}{2} \frac{\partial^2 \Phi_{\text{eff}}}{\partial R^2} \Big|_{(R_g, 0)} x^2 + \frac{1}{2} \frac{\partial^2 \Phi_{\text{eff}}}{\partial z^2} \Big|_{(R_g, 0)} z^2 + \frac{1}{2} \frac{\partial^2 \Phi_{\text{eff}}}{\partial x \partial z} \Big|_{(R_g, 0)} xz + \dots$$



0 (Φ_{eff} symmetric about $z=0$)

In Cartesian (x, z) frame,

$$\mathbf{a} = -\nabla \Phi_{\text{eff}}$$

$$\ddot{x} = -\frac{\partial \Phi_{\text{eff}}}{\partial x} \approx -\frac{\partial^2 \Phi_{\text{eff}}}{\partial R^2} \Big|_{(R_g, 0)} x \equiv -\kappa^2 x$$

$$\ddot{z} = -\frac{\partial \Phi_{\text{eff}}}{\partial z} \approx -\frac{\partial^2 \Phi_{\text{eff}}}{\partial z^2} \Big|_{(R_g, 0)} z \equiv -\nu^2 z$$

Harmonic oscillators with frequencies κ and ν

How to compute epicyclic frequency

Using definition $\Phi_{\text{eff}} = \Phi + \frac{L_z^2}{2R^2}$, $\kappa^2 = \left(\frac{\partial^2 \Phi}{\partial R^2} \right)_{(R_g, 0)} + \frac{3L_z}{R_g^4}$

Circular angular frequency: $\Omega^2 = \frac{1}{R} \left(\frac{\partial \Phi}{\partial R} \right)_{(R_g, 0)} = \frac{L_z^2}{R^4}$

(since for circular orbit

$$\partial \Phi / \partial R = R \dot{\phi}^2; \quad \Omega = \dot{\phi})$$

$$\begin{aligned} \Rightarrow \kappa^2(R_g) &= \left(\Omega^2 + R \frac{d\Omega^2}{dR} + 3\Omega^2 \right)_{R_g} = \left(R \frac{d\Omega^2}{dR} + 4\Omega^2 \right)_{R_g} \\ &= \frac{\partial^2 \Phi / \partial R^2}{3L_z / R_g^4} = \left(\frac{d\Omega^2}{d \ln R} + 4\Omega^2 \right)_{R_g} \end{aligned}$$

Elliptic motion around guiding center

$$x: \ddot{x} = -\kappa^2 x \quad \Rightarrow \quad x(t) = X \cos(\kappa t + \alpha) \quad \text{for } X \geq 0 \text{ and } \alpha \text{ constant}$$

$$y: \dot{\phi} = \frac{L_z}{R^2} \quad L_z = \text{const. in axisymmetric potential}$$

$$= \frac{L_z}{R_g^2} \left(1 + \frac{x}{R_g}\right)^{-2} \quad R = R_g + x = R_g(1 + x/R_g)$$

$$\approx \frac{L_z}{R_g^2} \left(1 - \frac{2x}{R_g}\right) \quad \text{Taylor expansion}$$

$$\Rightarrow \phi = \Omega_g t - \frac{2\Omega_g X}{R_g \kappa} \sin(\kappa t + \alpha) + \phi_0 \quad \text{integrating}$$

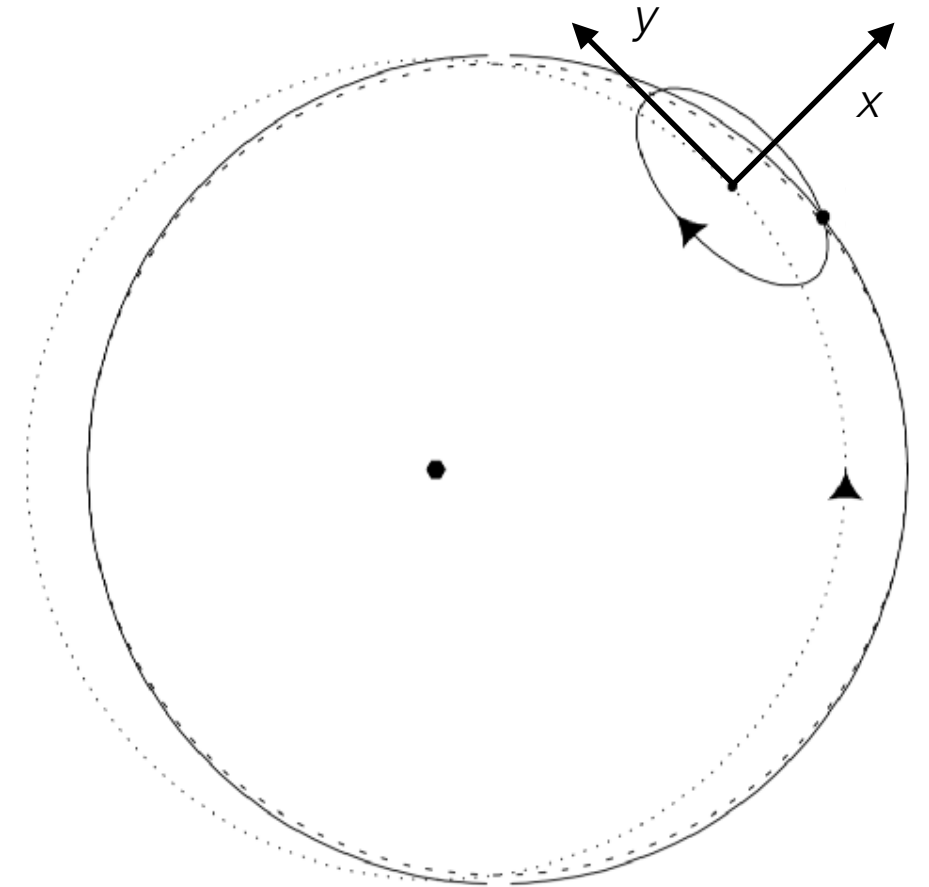
$$y \approx R_g(\phi - \phi_g) = -\frac{2\Omega_g X}{\kappa} \sin(\kappa t + \alpha) \equiv -Y \sin(\kappa t + \alpha)$$

Summary of epicyclic motion

$$x = X \cos(\kappa t + \alpha)$$

$$y = -Y \sin(\kappa t + \alpha)$$

$$z = Z \cos(\nu t + \xi) \quad \text{similarly as for } x$$



Elliptic motion in xy plane with aspect ratio

$$\frac{X}{Y} = \frac{\kappa}{2\Omega_g}$$

Motion around the epicycle is opposite in sense to the rotation of the guiding center. Conservation of $L_z = R^2 \dot{\phi} \Rightarrow \dot{\phi}$ decreases when R increases